III Year B.Tech. EEE – II Semester

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23A02604b	**ELECTRIC DRIVES (Professional Elective-III)**	**3**	**0**	**0**	**3**

Course Outcomes: After successful completion of the course, students will be able to:

CO1. Evaluate the characteristics and operational aspects of drives operating in different modes.**-L3**

CO2. Analyze the operational aspects of various controlled rectifiers fed DC drives operating in different sustainable modes of operation.**-L3**

CO3. Analyze the operational aspects of various controlled chopper fed DC drives operating in different sustainable modes of operation**.-L3**

CO4. Analyze the operational aspects of various asynchronous motor drives operating in different sustainable modes of operation. **-L3**

CO5. Analyze the operational aspects of synchronous motor and stepper motor drives operating in different sustainable modes of operation**. -L3**

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ntroduction To Electric Drives:

Electrical drives — block diagram, advantages of electric drive, parts of electric drives, choice of electrical drives, the status of DC and AC drives. Dynamics of electrical drives-fundamental torque equations, speed-torque conventions, and multi-quadrant operation; Equivalent values of drive parameters - loads with rotational and translational motion; Load torques — components, nature and classification. Concept of steady-state stability. Electric braking methods — regenerative, dynamic and plugging. Modes of operation of electrical drives — steady state, acceleration including starting and deceleration including stopping. Speed control and drive classifications, closed-loop control of drives — current limit control, torque control, speed control and position control (Block diagram only).

Unit II

Single-Phase and Three Phase Converter Fed DC Drives:

Control of DC separately excited motor by single-phase and three-phase half and full bridged converters — voltage and current waveforms for continuous and discontinuous conduction, speed-torque expressions and characteristics. Single phase half-controlled rectifier fed DC series motor — voltage and current waveforms for continuous and discontinuous conduction, speed-torque expressions and characteristics. Multi-quadrant operation of DC separately excited DC motor fed from fully controlled rectifier - mechanical reversible switch in armature, dual converter and field current reversal.

Unit III

DC Chopper Fed Drives:

Control of DC separately excited motor by one ,two and four quadrant choppers - voltage and current waveforms for continuous conduction (motoring, regenerative and dynamic braking), speed-torque expressions and characteristics. Chopper control of DC series motor—operation, speed-torque expressions and characteristics. Closed loop chopper control of separately excited DC motor (Block diagram only).

Unit IV

Induction Motor Drives:

Three phase induction motors — Introduction, Stator variable voltage control — speed-torque characteristics, AC voltage controllers and efficiency of induction motor under voltage control. Stator variable voltage and variable frequency control — slip speed control, torque-power limitations and modes of operation. Voltage Source Inverters (VSIs) and Current Source Inverters (CSIs) fed induction motor and closed loop operation of induction motor drives (Block diagram only).Comparison of VSI and CSI fed drives. Static rotor resistance control, slip power recovery schemes – static scherbius and kramer drive, speed-torque characteristics.

Unit V

Synchronous and Stepper Motor Drives:

Synchronous Motor Drives: Separate control and self-control of synchronous motors — operations of self-controlled synchronous motors by VSI and CSI. Load commutated CSI fed Synchronous motor—operation and speed torque characteristics. Closed loop control operation of synchronous motor drives (Block diagram only). Stepper Motor Drives: Variable reluctance and permanent magnet operation — features of stepper motor — torques Vs stepping rate characteristics and drive circuits. BLDC motor operation and control.

TEXT BOOKS:

1. Gopal K. Dubey, Fundamentals of Electric Drives, Narosa Publications, Alpha Science International Ltd, 2nd Edition, 2002.
2. M. H. Rashid (2003), Power Electronic Circuits, Devices and applications, 3rd edition, Prentice Hall of India, New Delhi, India.
3. Krishnan, Ramu. Electric motor drives: modeling, analysis, and control, 1st Edition, Pearson, 2015.

REFERENCE BOOKS:

1. M. D. Singh, K. B. Khanchandani (2008), Power Electronics, 2nd Edition, Tata McGraw Hill Publications, New Delhi.
2. VedamSubramanyam (2008), Thyristor Control of Electric drives, 1st Edition, Tata McGraw Hill Publications, New Delhi, India.
3. S. K. Pillai (2007), A First course on Electrical Drives, 2nd Edition, New Age International (P) Ltd.,NewDelhi
4. P.C. Sen, Principles of Electrical Machines and Power Electronics, Wiley, 3rdEdition, 2013.

ONLINE LEARNING RESOURCES:

1. https://web.iitd.ac.in/~amitjain/Drives_VTR.pdf
2. https://sde.uoc.ac.in/sites/default/files/sde_videos/Electrical%20Drives%20and%20Controls_0.pdf
3. https://nptel.ac.in/courses/108/104/108104140/
4. https://nptel.ac.in/courses/108/102/108102046/
5. https://swayam.gov.in/nd1_noc19_ee65/preview